



## **EFILive FlashScan Serial Protocol**

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# EFILive FlashScan Serial Protocol

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## Introduction

EFILive's FlashScan device may be configured to output OBDII PID data via its onboard RS232 serial port. External systems, such as dynamometers, can gain access to that PID data.

The RS232 serial port may also be used to transmit PID data to FlashScan for inclusion in the EFILive data logs.

This document describes how to configure FlashScan to output the serial PID data and the format of that data and how to transmit data to FlashScan and the format of the data to be transmitted.

## Prerequisites

For FlashScan V2 devices:

- You must be using software version: EFILive V8.1.2 Build 81 or later.
- You must be using firmware version: V2.06.21 or later.

For FlashScan V3 devices:

- You must be using software version: EFILive V8.3.17 or later.
- You must be using firmware version: V3.00.87 or later.

## Configuring FlashScan

Power up FlashScan, and select the following option:

For FlashScan V2:

1. F4: Options -> F1 Setup -> F1 Edit Settings.
2. Scroll down to the **COM Port** setting using the down arrow key.
3. Change the value to **Dyno** using the left or right arrow key.
4. Press Ok to save the changes.

Do not remove power from FlashScan while the blue LED is illuminated. The blue LED indicates that FlashScan is busy writing data to flash memory.

For FlashScan V3:

1. Options -> F1 Setup -> F1 Configuration.
2. Scroll down to the **COM Port Type** setting using the down arrow key.
3. Change the value to **External** using the left or right arrow key.
4. Press "Tick" to save the changes.

## The Serial Protocol

### COM Port Settings

5. Baudrate 57600.
6. Data Bits: 8.
7. Parity: None.
8. Stop Bits: 1.

### Data Frames

There are three types of data frames that FlashScan can transmit:

- F Frames, which list the names and units of the PIDs that return floating point values.
- S Frames, which list the names and units of the PIDs that return string values.
- V Frames, which contains the data values of all PIDs', listed in the F, B and S frames.

Previously a fourth frame type (B which was used for binary data) was supported. The binary frame type is now implemented via the S Frame.

There is one type of data frame that FlashScan can receive:

- D Frames, which are further subdivided by message IDs, each with different formats. Those formats are described later in this document.

### Data Format

Each frame transmitted/received by FlashScan follows this format:

**X** : ~ | <length><frame data><checksum>

Where **X** is one of:

- **F**, **S** or **V** for frames transmitted by FlashScan and;
- **D** for frames received by FlashScan.

: ~ | is a unique, static value that:

- a) Pads the frame's data to a long word boundary and;
- b) Provides a searchable ASCII marker for the start of a valid frame.

<length> is a 16 bit word indicating how many bytes (including the checksum) make up the frame.

<frame data> is an array of data bytes with format determined by the frame type.

<checksum> is a modulo 0x100 sum of all bytes in the frame (excluding the checksum byte).

**Transmitting Data to FlashScan**

Data that is transmitted to FlashScan must conform to one of EFILive’s pre-configured D Frames. Currently only three D Frames are available for transmitting PID data to FlashScan.

All numeric data in D frames are stored in Intel (least significant byte first) byte format.

**Message ID 0x7F01** is used to request PID names and units from FlashScan. See *Data Content Request* in the next section.

**Message ID 0x0100** is predefined to contain the following PIDs.

00000000	443A 7E7C 3F00 0001 0000 7A43 0000 1643	D:~ ?.....zC...C
00000010	52B8 5E3F 0000 C841 3400 CA42 0000 8C42	R.^?...A4..B...B
00000020	24B9 FC3D 0000 0C44 0000 7041 0000 7041	\$..=...D..pA..pA
00000030	0000 A040 0000 7A43 0000 7A43 0000 803F	...@...zC..zC...?
00000040	3333 4B41 5F	33KA_

Field	Description	Type	Hex Data	Factor	Offset	Data	Units
Frame Marker			443A7E7C			D:~	
Length	Number of data bytes	Word	3F00			63	Bytes
ID	Message ID	Word	0001			0x0100	
DYNTRQ	Torque	Float	00007A43	1	0	250.0	Nm
DYNPWR	Power	Float	00001643	1	0	150.0	kW
DYNLAMDA	Lambda	Float	52B85E3F	1	0	0.870	Lambda
DYNAAT	Ambient Air Temp	Float	0000C841	1	0	25.0	°C
DYNBARO	Barometric Pressure	Float	3400CA42	1	0	101.0	kPa
DYNRELHUM	Relative Humidity	Float	00008C42	1	0	70.0	%
DYNATMCOR	Atmospheric Correction	Float	24B9FC3D	1	0	0.1234	
DYNEGT1	EGT1	Float	00000C44	1	0	560.0	°C
DYNO2	O2	Float	00007041	1	0	15.0	%
DYNCO	CO	Float	00007041	1	0	15.0	%
DYNCO2	CO2	Float	0000A040	1	0	5.0	%
DYNHC	HC	Float	00007A43	1	0	250	ppm
DYNNOX	NOx	Float	00007A43	1	0	250	ppm
DYNCOCOR	COcor	Float	0000803F	1	0	1.00	
DYNAFR	Brettsneider (Gas calc'd)	Float	33334B41	1	0	12.70	AFR
Check sum		Byte	5F			0x5F	

Message ID 0x0200 is predefined to contain the following PIDs.

00000000	443A 7E7C 2D00 0002 EA14 B900 2C03 E902	D:~ -.....(...
00000010	6500 1803 4A03 2303 4E03 3F03 2703 3F03	e...J.#.N?.'.?..
00000020	5203 4303 4303 0800 1E00 1D00 3700 2C00	R.C.C.....7.,.
00000030	4A00 3B	J.5

Field	Description	Type	Hex Data	Factor	Offset	Data	Units
Frame Marker			443A7E7C			D:~ -	
Length	Number of bytes	Word	2D00			45	Bytes
ID	Message ID	Word	0002			0x0200	
FPERPM	RPM	Word	EA14	1	0	5354	rpm
FPEGPSSPD	Ground Speed	Word	B900	1	0	185	Km/h
FPEACCL	Acceleration	Word	2C03	0.0078125	-4	2.345	g-force
FPETURBO1	Turbo Speed 1	Word	E902	5.0	0	3728	rpm
FPETEMP1	Temperature 1	Word	6500	1	0	101	°C
FPETEMP2	Temperature 2	Word	1803	1	0	792	°C
FPETEMP3	Temperature 3	Word	4A03	1	0	842	°C
FPETEMP4	Temperature 4	Word	2303	1	0	803	°C
FPETEMP5	Temperature 5	Word	4E03	1	0	846	°C
FPETEMP6	Temperature 6	Word	3F03	1	0	831	°C
FPETEMP7	Temperature 7	Word	2703	1	0	807	°C
FPETEMP8	Temperature 8	Word	3F03	1	0	831	°C
FPETEMP9	Temperature 9	Word	5203	1	0	850	°C
FPETEMP10	Temperature 10	Word	4303	1	0	835	°C
FPETEMP11	Temperature 11	Word	4303	1	0	835	°C
FPEPRSR1	Pressure 1	Word	0800	6.894757	0	56	kPa
FPEPRSR2	Pressure 2	Word	1E00	6.894757	0	213	kPa
FPEPRSR3	Pressure 3	Word	1D00	6.894757	0	201	kPa
FPEPRSR4	Pressure 4	Word	3700	6.894757	0	382	kPa
FPEPRSR5	Pressure 5	Word	2C00	6.894757	0	307	kPa
FPEPRSR6	Pressure 6	Word	4A00	6.894757	0	514	kPa
Check sum		Byte	3B			0x3B	

**Message ID 0x0201** is predefined to contain the following PIDs.

00000000	443A 7E7C 2300 0102 0400 4148 0000 AD0A	D:~ #.....AH.....
00000010	3E03 6500 1803 4A03 2303 4E03 8400 8C00	>.e...J.#.N.....
00000020	8800 8500 8E00 8800 9A	.....

Field	Description	Type	Hex Data	Factor	Offset	Data	Units
Frame Marker			443A7E7C			D:~ #	
Length	Number of bytes	Word	2300			35	Bytes
ID	Message ID	Word	0102			0x0201	
FPESATS	Satellites in View	Word	0400	1	0	4	count
FPHEELVATION	Elevation	DWord	41480000	0.01	0	185	m
FPERPM2	RPM 2	Word	AD0A	1	0	2733	Rpm
FPETURBO2	Turbo Speed 2	Word	3E03	5.0	0	4152	Rpm
FPETEMP12	Temperature 12	Word	6500	1	0	101	°C
FPETEMP13	Temperature 13	Word	1803	1	0	792	°C
FPETEMP14	Temperature 14	Word	4A03	1	0	842	°C
FPETEMP15	Temperature 15	Word	2303	1	0	803	°C
FPETEMP16	Temperature 16	Word	4E03	1	0	846	°C
FPEPRSR7	Pressure 7	Word	8400	6.894757	0	911	kPa
FPEPRSR8	Pressure 8	Word	8C00	6.894757	0	967	kPa
FPEPRSR9	Pressure 9	Word	8800	6.894757	0	941	kPa
FPEPRSR10	Pressure 10	Word	8500	6.894757	0	920	kPa
FPEPRSR11	Pressure 11	Word	8E00	6.894757	0	985	kPa
FPEPRSR12	Pressure 12	Word	8800	6.894757	0	944	kPa
Check sum		Byte	9A			0x9A	

**Message ID 0x0202** is predefined to contain the following PIDs.

00000000	443A 7E7C 1D00 0202 9500 5401 2C01 3E00	D:~ .....T.,.>.
00000010	0100 1A0B D717 2E00 0B00 4300 2900 7901	.....C.) .y.
00000020	9301 B5	...

Field	Description	Type	Hex Data	Factor	Offset	Data	Units
Frame Marker			443A7E7C			D:~	
Length	Number of bytes	Word	1D00			29	Bytes
ID	Message ID	Word	0202			0x0202	
FPEANLGIN1	Analog Input 1 Voltage	Word	9500	2.44	0	365	mV
FPEANLGIN2	Analog Input 2 Voltage	Word	5401	2.44	0	832	mV
FPEANLGIN3	Analog Input 3 Voltage	Word	2C01	2.44	0	733	mV
FPEANLGIN4	Analog Input 4 Voltage	Word	3E00	2.44	0	153	mV
FPEDGTLIN1	Digital Input 1 State	Byte	01	0=Off 1=On	0	On	
FPEDGTLIN2	Digital Input 2 State	Byte	00	0=Off 1=On	0	Off	
FPEFREQIN1	Frequency Input 1	Word	1A0B	1	0	2842	Hz
FPEFREQIN2	Frequency Input 2	Word	D717	1	0	6103	Hz
FPEOUTPDC1	Output Duty Cycle 1	Word	2E00	1	0	46	%
FPEOUTPDC2	Output Duty Cycle 2	Word	0B00	1	0	11	%
FPEOUTPDC3	Output Duty Cycle 3	Word	4300	1	0	67	%
FPEOUTPDC4	Output Duty Cycle 4	Word	2900	1	0	41	%
FPEANLGOUT1	Analog Output 1 Voltage	Word	7901	2.44	0	920	mV
FPEANLGOUT2	Analog Output 2 Voltage	Word	9301	2.44	0	985	mV
Check sum		Byte	9A			0x9A	











**Unit Conversions**

Convert from	Convert To	Function
<b>Temperature</b>		
°F	°C	$C = (F-32)*5/9$
°C	°F	$F = C*9/5+32$
<b>Pressure</b>		
psi	kPa	$kPa = psi*6.894757$
kPa	Psi	$psi = kPa/6.894757$
<b>Speed</b>		
mph	kmh	$kmh=mph*1.609344$
kmh	mph	$mph=kmh/1.609344$
<b>Torque</b>		
ftlb	Nm	$Nm=ftlb*1.355818$
Nm	ftlb	$ftlb=Nm/1.355818$
<b>Power</b>		
hp	kW	$kW=hp*1.340483$
kW	hp	$hp=kW/1.340483$

### Receiving Data from FlashScan

For the remainder of this document, the examples shown are based on this LS1B PID selection.

Selected PIDs (per Menu Item)						
PID Name	Controller	Description	Units	Custom	Alarm	Channels
 MONDTC	PCM	Monitor Status Since DTCs Cleared				4
 RPM	PCM	Engine RPM (rpm)	rpm			2
 TP	PCM	Throttle Position (%)	%			1
 VSS	PCM	Vehicle Speed Sensor (kmh)	kmh			1
 ECT	PCM	Engine Coolant Temperature (°C)	°C			1
 MAP	PCM	Manifold Absolute Pressure (kPa)	kPa			1
 FUELSYS	PCM	Fuel System Status				2

Channel Allocation per Controller:  
 #1: 12/24: 

The image above is taken from the EFILive\_ScanAndTune.exe program in the Black Box Logging setup window.

More detailed information about each PID in the list above (including any sub-PIDs) can be obtained by right-clicking on the PID and selecting “More info...” from the “F5: Black Box Logging” option in the EFILive V8 Scan and Tune software.

**Data Content Request**

FlashScan will always transmit the complete set of PID values selected by the user. Because it is not possible for the receiving application to know the layout of the data frame in advance, FlashScan provides a method to query the names, formats and units of each of the PIDs that are being transmitted.

To query the PIDs' names, formats and units, you must transmit a D frame with the message ID 0x7F01 and one data byte (which is the checksum byte). The D frame may be transmitted at any time. The reply (a pair of F and S frames) will be transmitted after the current V frame or current pair of F and S frames has completed.

D Frame for requesting PID names:

00000000	443A 7E7C 0300 017F F9	D:~ .....
----------	------------------------	-----------

Field	Description	Hex Data	Formatted Data	Units
Frame Marker		0x443A7E7C	D:~	
Length	Number of data bytes	0x0300	3	Bytes
ID	Message ID	0x017F	0x7F01	
Check sum		0xFB	0xFB	

**Data Content Frames**

Frames F and S are returned in that order, in response to the Data Content request as described above.

Each Data Content frame is terminated with a null character 0x00 followed by the check sum byte.

**The F frame:**

00000000	463A 7E7C 3200 4454 4343 4E54 3D43 6F75	F:~ .2.DTCCNT=Count,RPM=rpm,TP=%,VSS=kmh,ECT=.C,MAP=kPa..
00000010	6E74 2C52 504D 3D72 706D 2C54 503D 252C	
00000020	5653 533D 6B6D 682C 4543 543D B043 2C4D	
00000030	4150 3D6B 5061 00CB	

**The S frame:**

00000000	533A 7E7C CF00 4D49 4C2C 4343 4D5F 5244	S:~ .MIL,CCM_RDY,FUEL_RDY,MIS_RDY,CCM_SUP,FUEL_SUP,MIS_SUP,EGR_SUP,HTR_SUP,O2S_SUP,ACRF_SUP,AIR_SUP,EVAP_SUP,HCAT_SUP,CAT_SUP,EGR_RDY,HTR_RDY,O2S_RDY,ACRF_RDY,AIR_RDY,EVAP_RDY,HCAT_RDY,CAT_RDY,FUELSYS1,FUELSYS2.p
00000010	592C 4655 454C 5F52 4459 2C4D 4953 5F52	
00000020	4459 2C43 434D 5F53 5550 2C46 5545 4C5F	
00000030	5355 502C 4D49 535F 5355 502C 4547 525F	
00000040	5355 502C 4854 525F 5355 502C 4F32 535F	
00000050	5355 502C 4143 5246 5F53 5550 2C41 4952	
00000060	5F53 5550 2C45 5641 505F 5355 502C 4843	
00000070	4154 5F53 5550 2C43 4154 5F53 5550 2C45	
00000080	4752 5F52 4459 2C48 5452 5F52 4459 2C4F	
00000090	3253 5F52 4459 2C41 4352 465F 5244 592C	
000000A0	4149 525F 5244 592C 4556 4150 5F52 4459	
000000B0	2C48 4341 545F 5244 592C 4341 545F 5244	
000000C0	592C 4655 454C 5359 5331 2C46 5545 4C53	
000000D0	5953 3200 70	

**The Data Value Frame**

The V frame contains a non-delimited list of all the floating-point PIDs' values and a comma separated list of all the string PIDs' values determined by the F and S frames.

The length of the frame is determined by the number and format of the PIDs listed in the F and S frames.

For FlashScan V2: V Frames are transmitted 10 times per second.

For FlashScan V3: V Frames are transmitted at the same rate that frames are logged on the V3 device. Many CAN based vehicles log data at 40 frames per second (or sometimes faster) which can saturate the RS232 serial link when a large number of PIDs are being logged. In that case frames will be skipped.

At 57600 baud, the RS232 serial link can transmit about 5,000 bytes per second, which is about 125 bytes at 40 frames per second. So, a good rule of thumb to prevent frame skipping is to reduce the PID selection so that the total length of the V frame is 125 bytes or less.

The format of the V frame is:

- A 4 byte unique frame marker: **V : ~ |**
- A 2 byte count in Intel (least significant byte first) byte format of the number of bytes left in the frame, including the checksum byte.
- A 4 byte timestamp in Intel (least significant byte first) byte format. The timestamp represents the number of milliseconds since the log was started.
- A 4 byte (32 bit) flag value.
  - For FlashScan V2 devices, only the first 8 bits are defined and those 8 bits correspond to the F1..F4 and Ctrl+F1..Ctrl+F4 keys that may have been pressed by the user to mark some significant event during data logging.
  - For FlashScan V3 devices, only the first 4 bits are defined and those 4 bits correspond to the Left, Right, Fn+Left and Fn+Right keys that may have been pressed by the user to mark some significant event during data logging.
- IEEE floating point values in Intel (least significant byte first) byte format. There will be as many 4 byte floating point values as are defined in the F frame.
- Comma separated strings. There will be as many comma separated strings as are defined in the S frame. A string value will never exceed 12 bytes in length. The last string is followed by a null terminator.
- A checksum byte which contains a "modulo 256" checksum of all the previous bytes in the V frame.

Example V Frame:

00000000	563A 7E7C 7C00 2A15 0000 0000 0000 0000	V:~   .*****
00000010	0000 0000 0000 0000 0000 0000 0000 0000	.....
00000020	1CC2 0000 2041 4F66 662C 5965 732C 5965	.... AOff, Yes, Ye
00000030	732C 5965 732C 5965 732C 5965 732C 5965	s, Yes, Yes, Yes, Ye
00000040	732C 5965 732C 5965 732C 5965 732C 4E6F	s, Yes, Yes, Yes, No
00000050	2C4E 6F2C 5965 732C 4E6F 2C59 6573 2C4E	, No, Yes, No, Yes, N
00000060	6F2C 4E6F 2C4E 6F2C 5965 732C 5965 732C	o, No, No, Yes, Yes,
00000070	4E6F 2C59 6573 2C59 6573 2C4F 4C2C 4F4C	No, Yes, Yes, OL, OL
00000080	00FF	.f

Field	Hex Data	Formatted Data	Units
Frame Marker	0x563A7E7C	V:~	
Length	0x7C00		
Timestamp	0x2A150000	00:00:05.418	
Flags	0x00000000		
DTCCNT	0x00000000	0	Count
RPM	0x00000000	0	Rpm
TP	0x00000000	0	%
VSS	0x00000000	0	kmh
ECT	0x00001CC2	-39	°C
MAP	0x00002041	10	kPa
MIL	0x4F6666	Off	
CCM_RDY	0x596573	Yes	
FUEL_RDY	0x596573	Yes	
MIS_RDY	0x596573	Yes	
CCM_SUP	0x596573	Yes	
FUEL_SUP	0x596573	Yes	
MIS_SUP	0x596573	Yes	
EGR_SUP	0x596573	Yes	
HTR_SUP	0x596573	Yes	
O2S_SUP	0x596573	Yes	
ACRF_SUP	0x4E6F	No	
AIR_SUP	0x4E6F	No	
EVAP_SUP	0x596573	Yes	
HCAT_SUP	0x4E6F	No	
CAT_SUP	0x596573	Yes	
EGR_RDY	0x4E6F	No	
HTR_RDY	0x4E6F	No	
O2S_RDY	0x4E6F	No	
ACRF_RDY	0x596573	Yes	
AIR_RDY	0x596573	Yes	
EVAP_RDY	0x4E6F	No	
HCAT_RDY	0x596573	Yes	
CAT_RDY	0x596573	Yes	
FUELSYS1	0x4F4C	OL	

FUELSYS2	0x4F4C	OL	
Check sum	0xFF	0xFF	

**Future developments**

- Allow data logging to be started/stopped using commands sent on the serial link.
- Allow PID selection to be changed using commands sent on the serial link.
- If/when PID selection is allowed to be changed “on the fly”; embedded F and S frames would indicate the new PID selection without being requested by the receiving application.
- Additional frames for storing Meta data such as customer and vehicle details may be added in future. Those frames will start with the standard **X:~!** sequence where “X” is a letter other than the existing F, S or V frame identifiers. For forward compatibility, if you encounter a frame with an identifier other than F, S or V, you may simply ignore it.